

Key: **IEEE JNL** = IEEE Journal or Magazine, **IEE JNL** = IEE Journal or Magazine, **IEEE CNF** = IEEE Conference, **IEE CNF** = IEE Conference, **IEEE STD** = IEEE Standard

1. A Calibration Method for MEMS Inertial Sensors Based on Optical Tracking

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2. Maintaining stereo calibration by tracking image points

Crowley, J.L.; Bobet, P.; Schmid, C.;

Computer Vision and Pattern Recognition, 1993. Proceedings CVPR '93., 1993 IEEE Computer Society Conference on

15-17 June 1993 Page(s):483 - 488

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4. Robotics and structural dynamics characterization of the space station remote manipulator system using photogrammetric techniques

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5. μ IMU-based handwriting recognition calibration by optical tracking

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6. Numerical optimization on the Euclidean group with applications to camera calibration

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8. Adaptive visual servoing in the presence of intrinsic calibration uncertainty

Chen, J.; Behal, A.; Dawson, D.M.; Dixon, W.E.;
Decision and Control, 2003. Proceedings. 42nd IEEE Conference on
Volume 5, 9-12 Dec. 2003 Page(s):5396 - 5401 Vol.5

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9. Image registration using a 3-D scene representation

Zhaohui Sun; Tekalp, A.M.;
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10. Three-dimensional location estimation of circular features for machine vision

Safaei-Rad, R.; Tchoukanov, I.; Smith, K.C.; Benhabib, B.;
Robotics and Automation, IEEE Transactions on
Volume 8, Issue 5, Oct. 1992 Page(s):624 - 640

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11. An analytical method for the 3D-location estimation of circular features for an active-vision system

Safaei-Rad, R.; Smith, K.C.; Benhabib, B.; Tchoukanov, I.;
Systems, Man and Cybernetics, 1990. Conference Proceedings., IEEE International Conference on
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